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;

; Author : ADI - Apps

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; Date : January 2001

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; File : Tx1to10.asm

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; Hardware : ADuC816

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; Description : This Program transmits the numbers 1-10 in binary

; form continuously down the spi port.

; After the transmission of each byte the incoming

; byte is saved in order between internal RAM

; addresses 40h and 50h.

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; An SPI slave program can be run on a second device

; (ADuC824/ADuC816/AduC812) to communicate with

; this master code.

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; The Slave program (tx11to20.asm in the SPI\SLAVE

; directory) should be started after the master

; program (tx1to10.asm) but within the time delay

; of 5s in order that the slave program is

; synchronised by the first outputted clock of the

; master.

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; The clock is outputted at sclock (pin 26)

; The data is outputted at sdata/MOSI (pin 27)

; The data is inputted at MISO (pin 14)

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$MOD816 ;Use 8052 / ADuC816 predefined Symbols

LED EQU P3.4

FLAG BIT 00H

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; BEGINNING OF CODE

CSEG

ORG 0000H

JMP MAIN

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; SPI INTERRUPT ROUTINE

ORG 003BH

SETB P3.5 ; set the SS bit after transmission

CLR FLAG ; Clear flag to leave loop

MOV @R1, SPIDAT ; move input into memory

INC R1 ; increment memory location so new

; data is stored in new address

CJNE R1, #50H, CONT ; check if memory location =50h.

; if not continue

MOV R1, #40H ; if so reset address to 40h to store

; the next 16 bytes to the same

; memory locations

CONT: RETI

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ORG 0060H ; Start code at address above interrupts

MAIN: ; Main program

MOV SPICON,#037h ; Initialise SPICON to have

; -bitrate=fosc/64

; -CPHA=1

; -CPOL=0, sclk idling low

; -master mode select

; -Enable SPI serial port

MOV IEIP2, #01h ; Enable SPI interrrupt

SETB EA ; Enable Global Interrupts

MOV R1, #40h ; initialise R1 to 40 to store the

; input data from memory location 40

MOV R0, #00H ; initialise R0 to 0 to start

; transmissions from 1

; Delay the output of data by 5.0s in order that the slave program

; can be easily synchronised with the master program.

MOV A, #50

CALL DELAY

TRNSMT:

CLR P3.5 ; clear the SS bit during transmission

INC R0

MOV SPIDAT, R0 ; transmit the current value on R0

SETB FLAG ; set flag so that we wait here until

; the spi interrupt routine clears

; the FLAG

JB FLAG, $ ; stay here until flag is cleared

; by interrupt

; check if R0 is equal to 10. If so the number 10 has been

; transmitted and we should reset R0 to 0 to start transmission

; from 1 again

MOV A, R0

CJNE A, #0AH, TRNSMT ; if R0 is not 10, jump to TRNSMT

MOV R0, #00H ; if R0=10 make R0=0 & jump to TRNSMT

JMP TRNSMT

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; SUBROUTINES

DELAY: ; Delays by 13,000 \* A instructions (approx)

; 100mSec based on 1.5728MHZ Core Clock (default)

MOV R0,A ; Acc holds delay variable

DLY0: MOV R1,#65 ; Set up delay loop0

DLY1: MOV R2,#200 ; Set up delay loop1

DJNZ R2,$ ; Dec R2 200 times

DJNZ R1,DLY1 ; Dec R1 65 times

DJNZ R0,DLY0 ; Dec R0 #ACC times

RET ; Return from subroutine

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END